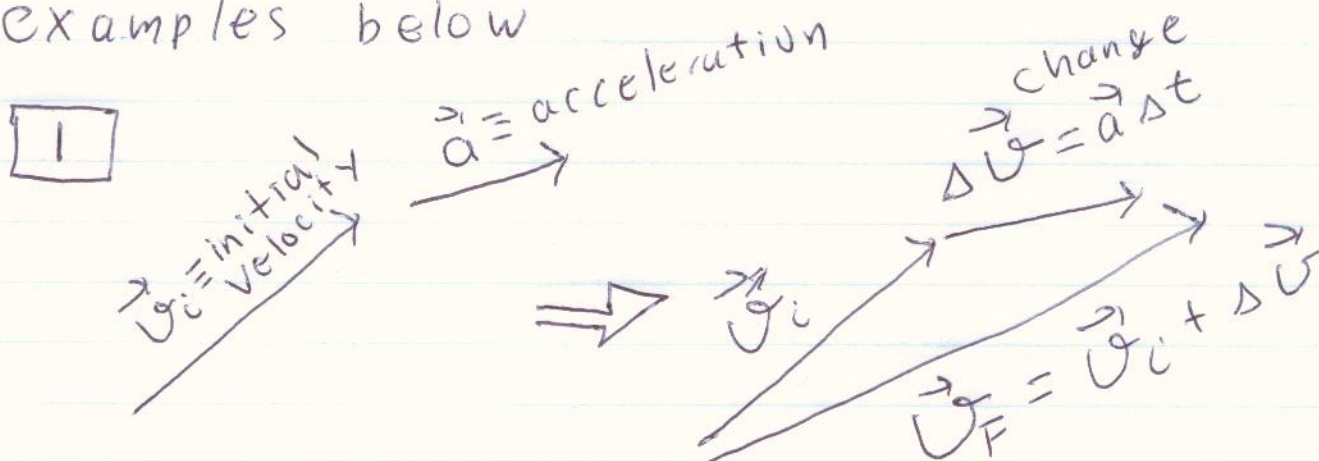
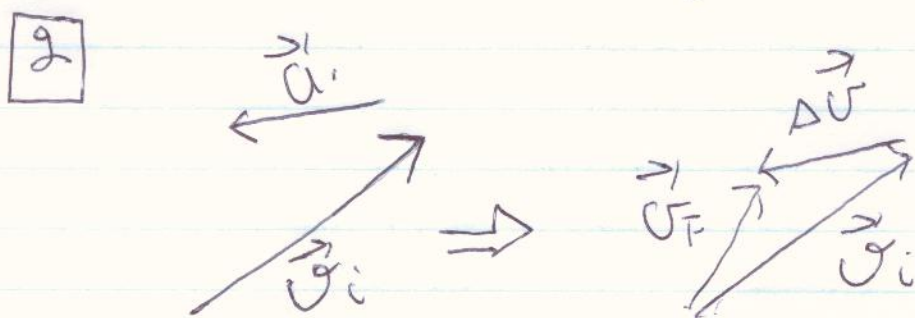


Speeding up/slowing down & turning Left/Right

acceleration \vec{a} is the rate of change of velocity $\Delta\vec{v}/\Delta t$. Consider an object moving at a velocity \vec{v} and acceleration \vec{a} . To determine the effect of \vec{a} on \vec{v} , assume \vec{a} lasts for a period Δt to create a change in velocity $\Delta\vec{v} = \vec{a}\Delta t$. Consider the examples below

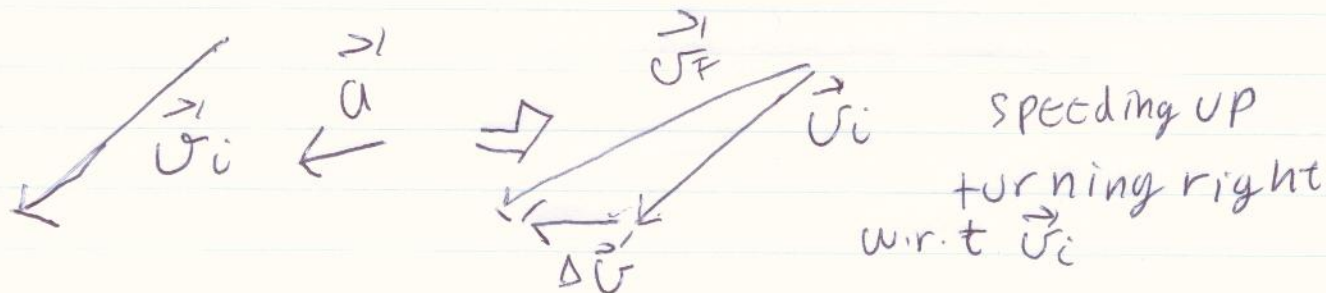


$v_f > v_i$ speeding up
turning right w.r.t \vec{v}_i

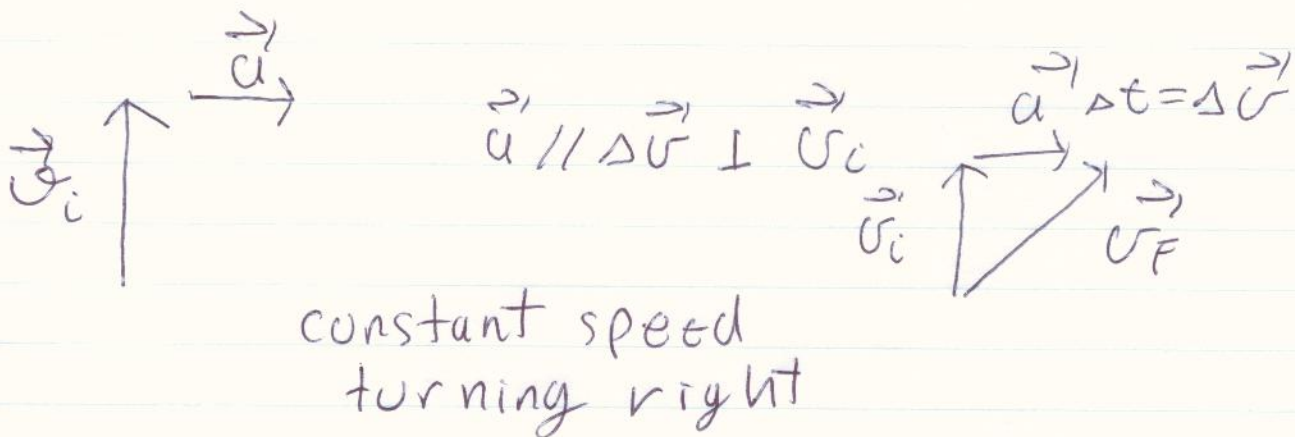


$v_f < v_i$ slowing down
turning left

3



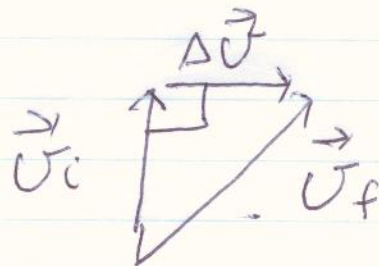
4



BUT IS THERE A PROBLEM?

Consider again (4)

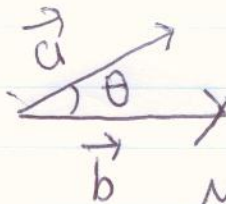
Using Pythagoras' theorem $v_f > v_i$



So the speed shouldn't be constant


Resolution The reason for this apparent contradiction is due to the fact that when $\vec{v} \perp \vec{a}$ it is no longer appropriate to use $\Delta t > 0$, but instead we must use the limit $\Delta t \rightarrow 0$.

Math Preamble scalar product section 3.8 pp47-49

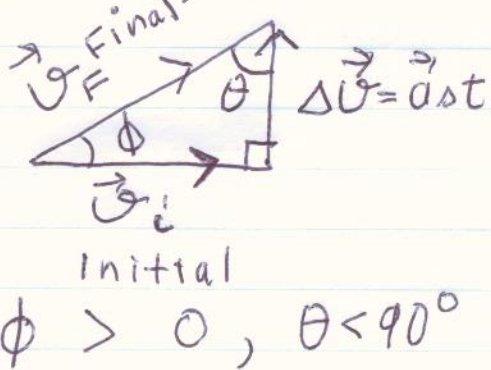

 $\vec{a} \cdot \vec{b} = ab \cos \theta \rightarrow$ if $\vec{a} \perp \vec{b} \quad \theta = 90^\circ$
 $\vec{a} \cdot \vec{b} = ab \cos 90^\circ = 0$

magnitude of \vec{a} : $|\vec{a}| = a = \sqrt{\vec{a} \cdot \vec{a}}$
 or $a^2 = \vec{a} \cdot \vec{a}$

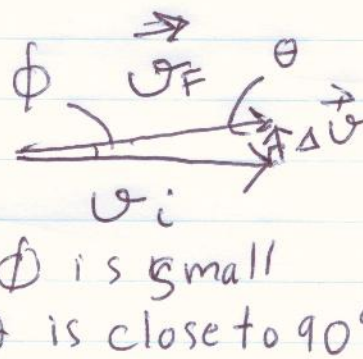
Consider Again an object moving with \vec{v} & acceleration $\vec{a} \perp \vec{v}$



i) Finite time
 $\Delta t > 0, \Delta \vec{v} = \vec{a} \Delta t$



ii) Small time
 $\Delta t \ll 1$



iii) Calculus limit
 $\Delta t \rightarrow 0$
 $\phi \rightarrow 0$
 $\theta \rightarrow 90^\circ$

Hence as $\Delta t \rightarrow 0$ $\Delta \vec{v}$ is \perp to \vec{v}_F & \vec{v}_i
 $\Delta \vec{v} \cdot \vec{v}_i = 0$ & $\Delta \vec{v} \cdot \vec{v}_F = 0$

Consider square Final speed

$$v_F^2 = \vec{v}_F \cdot \vec{v}_F = \vec{v}_F \cdot (\vec{v}_i + \Delta \vec{v})$$

$$v_F^2 = \vec{v}_F \cdot \vec{v}_i + \vec{v}_F \cdot \Delta \vec{v}$$

Zero

$$= (\vec{v}_i + \Delta \vec{v}) \cdot \vec{v}_i$$

$$v_F^2 = \vec{v}_i \cdot \vec{v}_i + \Delta \vec{v} \cdot \vec{v}_i$$

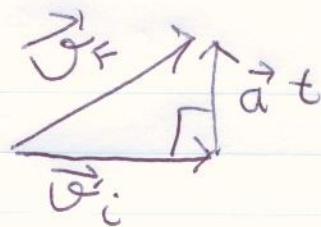
Zero

$$v_F^2 = v_i^2$$

Q.E.D

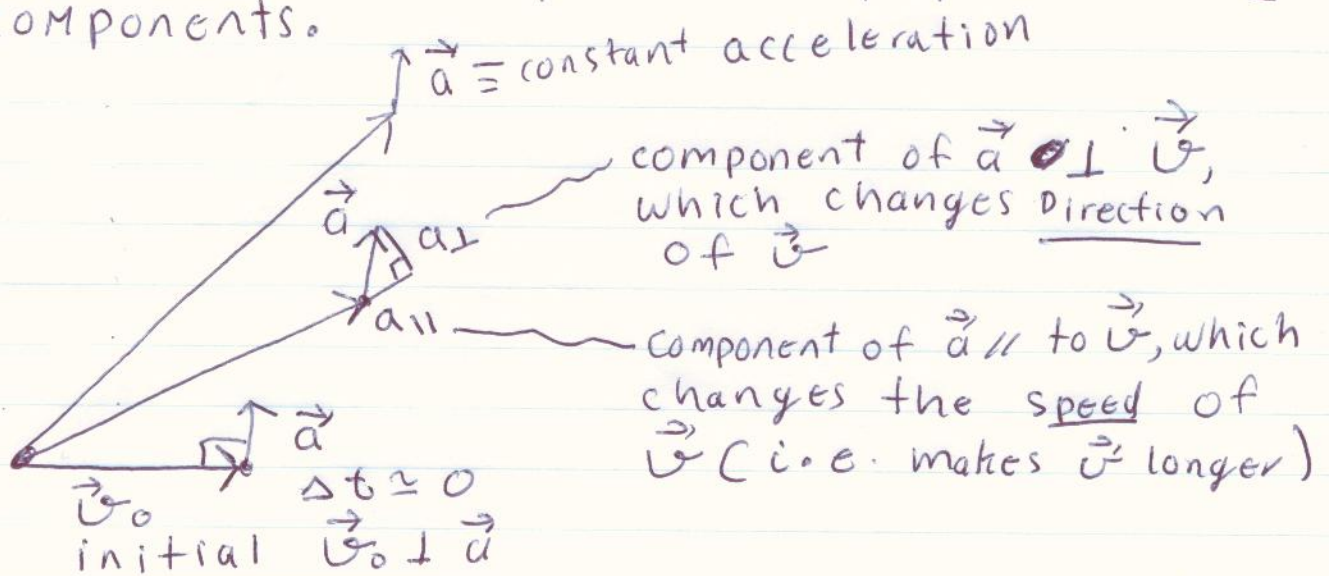
Final speed $v_F = v_i$ initial speed

Why for finite $\Delta t > 0$

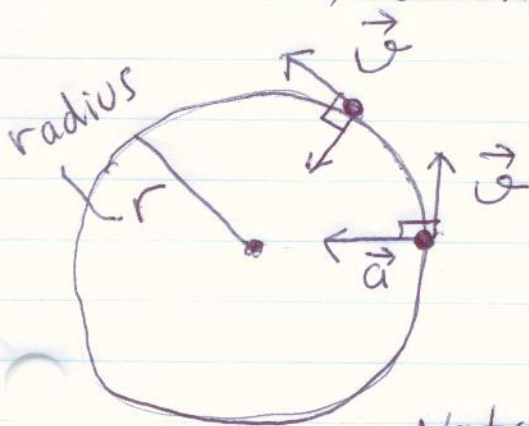


gives $v_f > v_i$?

ANSWER Initially $\Delta t \approx 0$ & acceleration \vec{a} is perpendicular \perp to velocity \vec{v} . But as $\Delta t > 0$ increases the velocity $\vec{v}_f = \vec{v}_i + \vec{a} \cdot \Delta t$ will no longer be \perp to \vec{a} , instead \vec{a} will have parallel $a_{||}$ & perpendicular a_{\perp} components.



For UNIFORM CIRCULAR MOTION the acceleration \vec{a} is constantly changing direction so that \vec{a} is always \perp \vec{v} , and \vec{v} is constantly changing ^{while} its speed v remains constant.



\vec{v} is always \parallel to the circle
 " " " \perp to \vec{a}
 \vec{a} always points to center
 magnitude $a = v^2 / r$

Note: For uniform circular motion $v \equiv \text{constant}$. If \vec{v} is not constant \vec{a} can have both a_{\perp} & $a_{||}$.