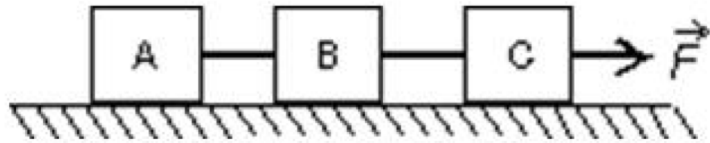


# Newton's Law

Theory and Problems

# A Multiple Choice: Part I

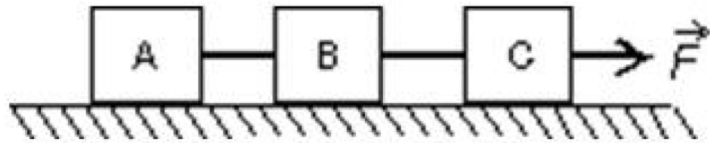
- Three blocks (A, B, C), each having the same mass  $M$ , are connected by strings as shown. Block C is pulled to the right by a force that causes the entire system to accelerate. Neglecting friction, the **net force** acting on block B is:



- A) 0; B)  $\vec{F}/3$ ; C)  $\vec{F}/2$ ; D)  $2\vec{F}/3$ ; E)  $\vec{F}$**
- Solution: Composite System and Newton second law
- $F = 3Ma \rightarrow a = \frac{F}{3M}$
- Net force on any box:  $F_{net,1box} = Ma = \frac{F}{3}$ , **B**

# A Multiple Choice: Part II

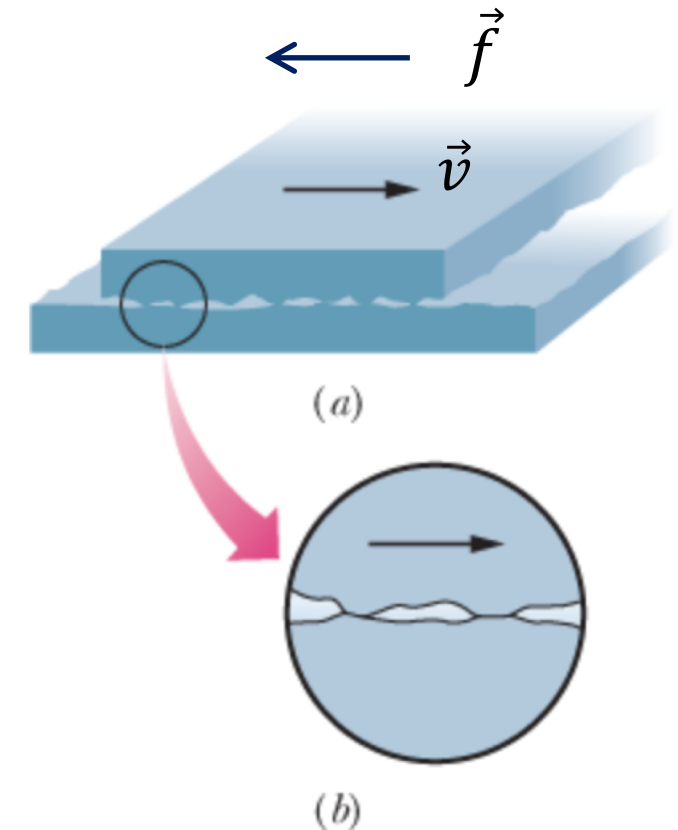
- Three blocks (A, B, C), each having the same mass  $M$ , are connected by strings as shown. Block C is pulled to the right by a force that causes the entire system to accelerate. Neglecting friction, the **Tension in rope** connecting B and C:



- A) 0; B)  $\vec{F}/3$ ; C)  $\vec{F}/2$ ; D)  $2\vec{F}/3$ ; E)  $\vec{F}$**
- Solution: Composite System and Newton second law
- $F = 3Ma \rightarrow a = \frac{F}{3M}$
- Net force on any box:  $F_{net,1box} = Ma = \frac{F}{3}$
- Horizontal force on C gives  $F - T_{BC} = F_{net,1box} = \frac{F}{3} \rightarrow T_{BC} = \frac{2F}{3}$ . **D**

# Friction Section 6.1

- In Figure 6.1.1 (a) a top slab sliding over a bottom slab experiences a friction force,  $\vec{f}$ , opposing its motion.
- Friction is due to the microscopic contacts between the two surfaces. This is seen in Figure 6.1.1 (b).
- The friction depends on the properties of the surface, such as its molecular makeup, and its smoothness/roughness.



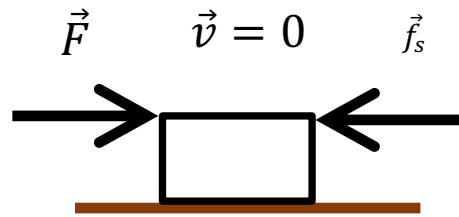
**Figure 6.1.1**

# Static and Kinetic Friction

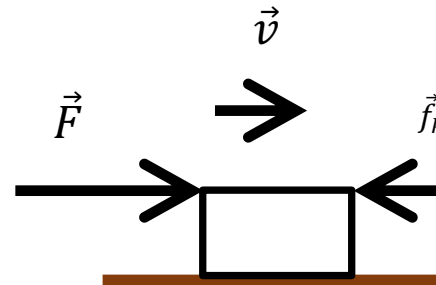
When a Force,  $\vec{F}$ , is applied to an object at **rest** on a **surface** with **friction**, there is a **force of static friction**,  $\vec{f}_s$ , that cancels the applied force **up to a maximum value**:

$$f_{s,max} = \mu_s F_N > f_s$$

where  $\mu_s$  is the coefficient of static friction



$$\vec{F} = \vec{f}_s$$
$$\vec{F}_{Net} = \vec{F} - \vec{f}_s = 0$$



$$\vec{F} > \vec{f}_k$$
$$\vec{F}_{Net} = \vec{F} - \vec{f}_k > 0$$

If the object is moving with a velocity,  $\vec{v}$ , on a **surface** with **friction**, there is a **force of kinetic friction**,  $\vec{f}_k$  in the opposite direction of the velocity, with a magnitude:

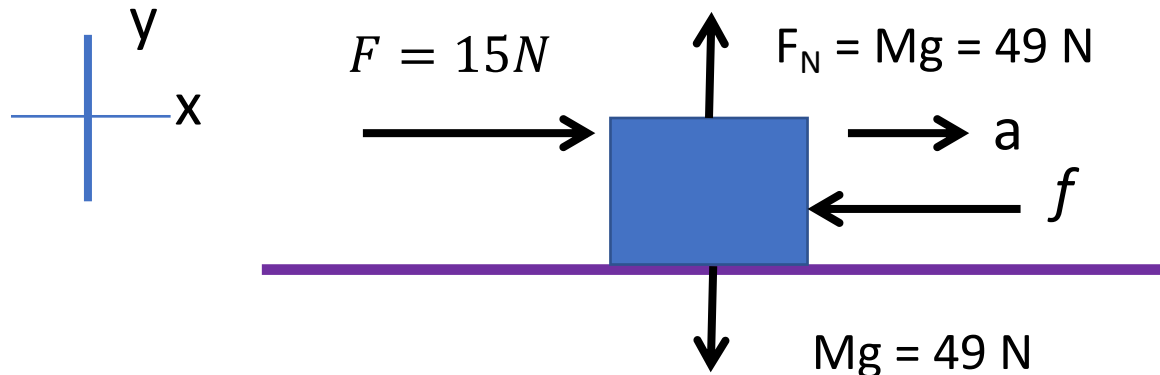
$$f_k = \mu_k F_N$$

where  $\mu_k$  is the coefficient of kinetic friction.

If an object at rest is acted on by an applied  $F > f_{s,max}$ , the object will move and the friction force equals  $f_k = \mu_k F_N$

# Simple Friction Problem I

- Below is a box of mass  $M = 5 \text{ kg}$  at **rest** on a surface with friction coefficient,  $\mu_k = 0.15$  and  $\mu_s = 0.3$ . A horizontal force  $F = 15 \text{ N}$  is applied. Calculate the force of Friction and acceleration.



$$\begin{aligned} \text{Y-comp: } F_{Net,y} &= F_N - Mg = 0 \\ F_N &= 49 \text{ N} \end{aligned}$$

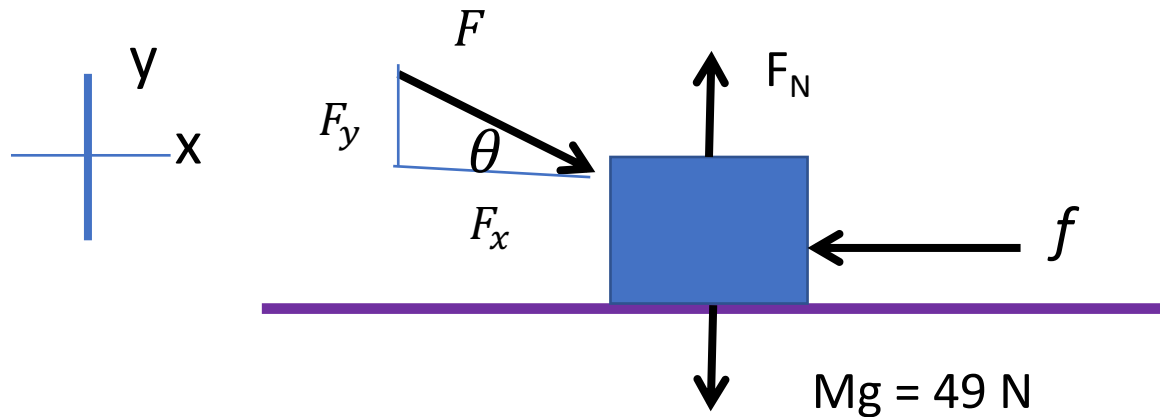
Maximum Friction:  $f_{s,max} = \mu_s F_N = 14.7 \text{ N}$   
 $F = 15 \text{ N} > 14.7 \text{ N}$ . It will Move!

$$\text{Kinetic Friction: } f_k = \mu_k F_N = 7.35 \text{ N}$$

$$\begin{aligned} \text{Newton's 2}^{\text{nd}} \text{ Law: } F_{Net,x} &= F - f_k = Ma \\ 15 \text{ N} - 7.35 \text{ N} &= 5 \text{ kg} \times a \\ \underline{a} &= \underline{1.53 \text{ m} \cdot \text{s}^{-2}} \end{aligned}$$

# Simple Friction Problem II

- Below is a box of mass  $M = 5 \text{ kg}$  at **rest** on a surface with friction coefficient,  $\mu_k = 0.15$  and  $\mu_s = 0.3$ . A force  $F = 15 \text{ N}$ , applied at angle  $\theta = 36.9^\circ$  is applied. Calculate the force of Friction and acceleration.



$$\text{Y-comp: } F_{Net,y} = F_N - F \sin \theta - Mg = 0$$

$$F_N = 15\text{N} \times 0.6 + 49\text{N} = 58\text{N}$$

$$\text{Maximum Friction: } f_{s,max} = \mu_s F_N = 17.8\text{N}$$

$$F_x = 15\text{N} \cos \theta = 12\text{N} < 17.8\text{N}$$

$F_x$  cannot overcome static friction

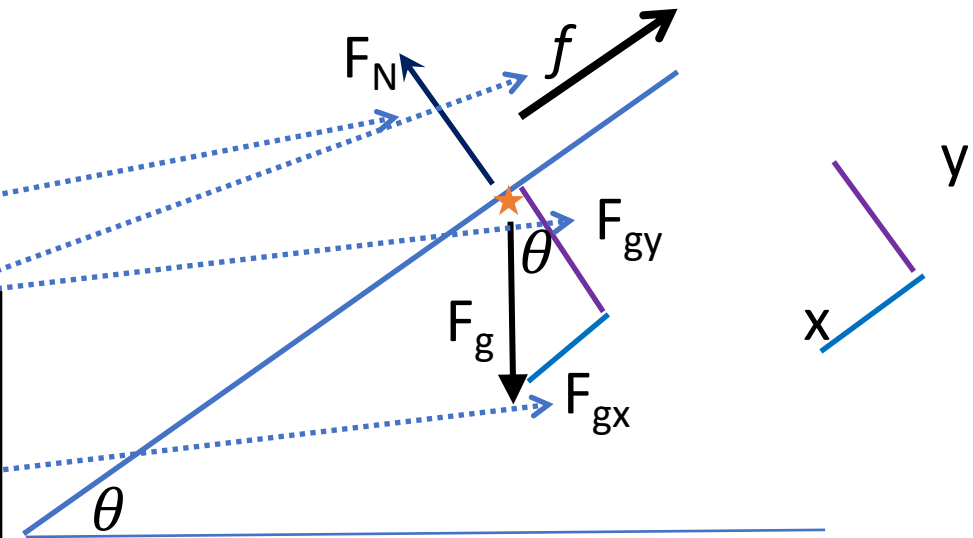
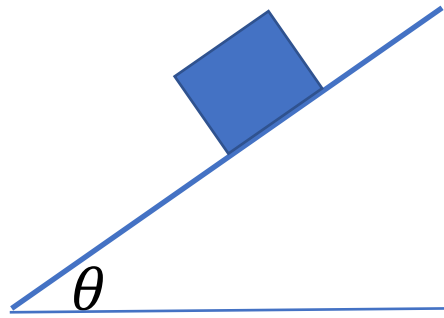
Friction force is static,  $f_s$

$$\begin{aligned} F_{Net,x} &= F_x - f_s = 0 \\ f_s &= 15\text{N} \cos \theta = 12\text{N} \\ \underline{a} &= \underline{0} \end{aligned}$$

# Incline with Friction Problem I

- A **box** of mass  $m = 8 \text{ kg}$  is **resting** on a  $\theta = 36.9^\circ$  incline, with  $\mu_k = 0.4$  and  $\mu_s = 0.8$ .
- Find the force of friction and the acceleration.

Direction of friction,  $\vec{f}$ , is **opposite** direction of motion ... or **possible motion**



Draw FBD

$$\text{Y-com: } F_{Net,y} = F_N + F_{gy} = 0$$

$$F_N - mg \cos 36.9 = 0 \rightarrow F_N = 62.72 \text{ N}$$

$$\text{Maximum Static Friction: } f_{s,max} = F_N \mu_s = 50.176 \text{ N}$$

$$F_{gx} = mg \sin 36.9 = 47.04 \text{ N} < f_{s,max}$$

$F_{gx}$  cannot overcome static friction:

Acceleration is zero!

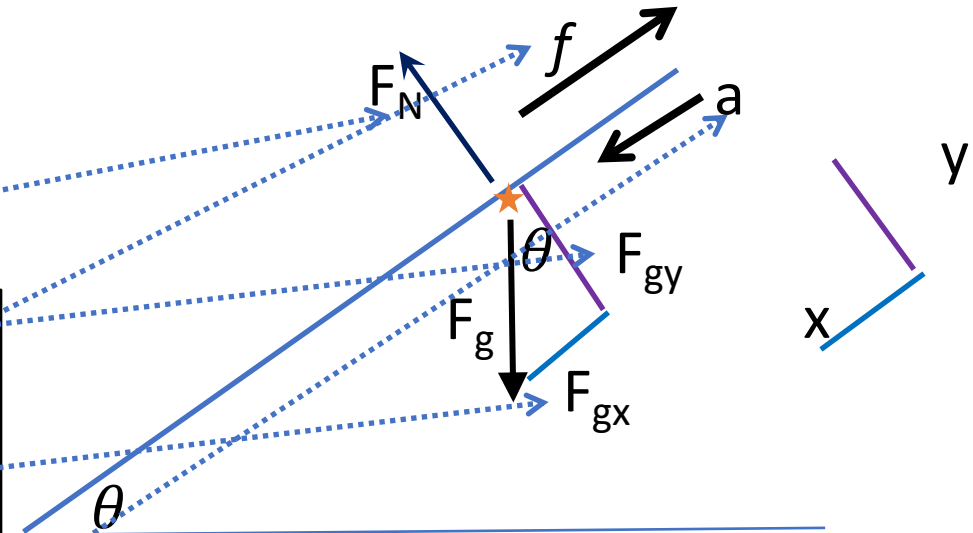
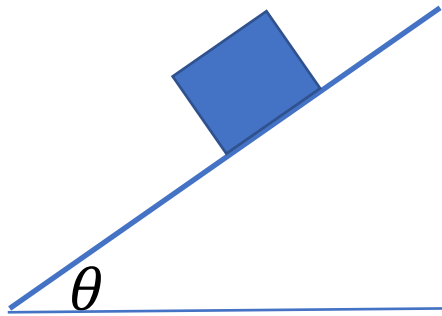
$$\text{X-comp: } F_{Net,x} = F_{gx} - f_s = 0 \rightarrow f_s = 47.04 \text{ N}$$



# Incline with Friction Problem II

- A **box** of mass **m = 8 kg** is **resting** on a  $\theta = 53.1^\circ$  incline, with  $\mu_k = 0.4$  and  $\mu_s = 0.8$ .
- Find the force of friction and the acceleration.

Direction of friction,  $\vec{f}$ , is **opposite** direction of motion ... or **possible motion**



Draw FBD

Y-com:  $F_{Net,y} = F_N + F_{gy} = 0$

$$F_N - mg \cos 53.1 = 0 \rightarrow F_N = 47.04N$$

Maximum Static Friction:  $f_{s,max} = F_N \mu_s = 37.632N$

$$F_{gx} = mg \sin 53.1 = 62.72N > f_{s,max}$$

$F_{gx}$  overcome static friction

Kinetic Friction,  $f_k = f = F_N \mu_k = 18.8N$

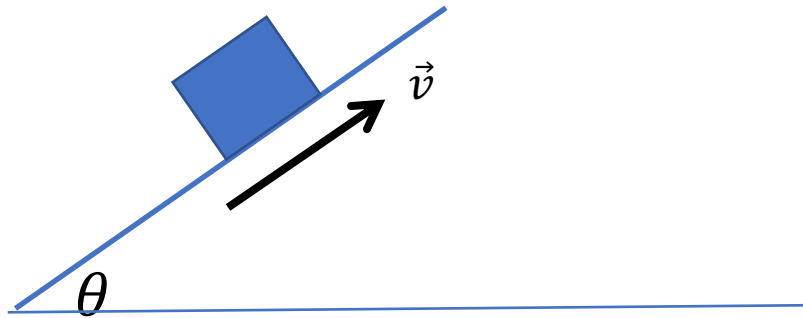
X-comp:  $F_{Net,x} = F_{gx} - f_k = ma \rightarrow a = 5.49m \cdot s^{-2}$

What if the box is moving down?  
 Would the acceleration change?.....No!  
 Friction will still be up incline, and  $a = 5.49m \cdot s^{-2}$ !

# Incline with Friction Problem III, moving up

- A **box** of mass **m = 8 kg** is **moving up** a  $\theta = 53.1^\circ$  incline, with  $\mu_k = 0.4$  and  $\mu_s = 0.8$ .
- Find the force of **friction** and the **acceleration**.

Direction of friction,  $\vec{f}$ , is **opposite** direction of **motion**.



Draw FBD

Y-com:  $F_{Net,y} = F_N + F_{gy} = 0$

$$F_N - mg \cos 53.1^\circ = 0 \rightarrow F_N = 47.07 \text{ N}$$

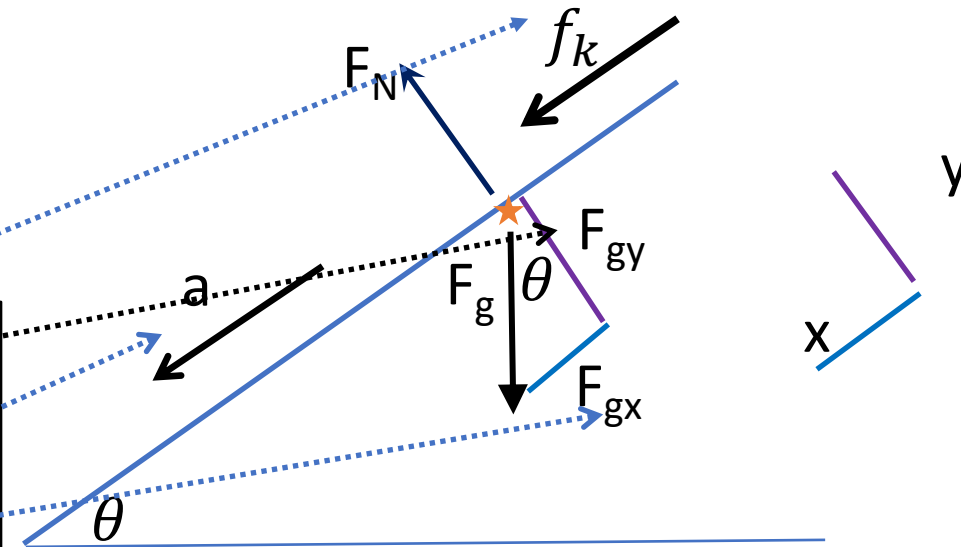
Since already moving, **Kinetic Friction**:

$$f_k = F_N \mu_k = 18.8 \text{ N}$$

$$F_{gx} = mg \sin 53.1^\circ = 62.7 \text{ N}$$

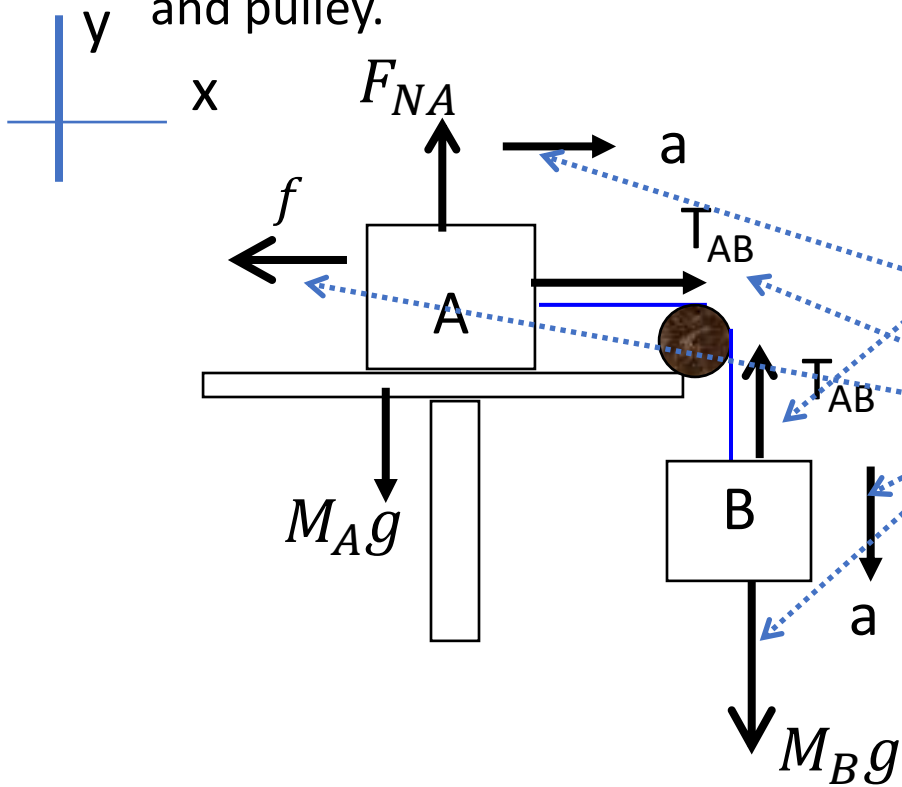
X-comp:  $F_{Net,x} = F_{gx} + f_k = ma$

$$\text{Acceleration: } a = \frac{62.7 \text{ N} + 18.8 \text{ N}}{8 \text{ kg}} = 10.18 \frac{\text{m}}{\text{s}^2}$$



# 2-Body with friction I

In the diagram below block A has a mass of 4.00 kg and block B has mass 8.00 kg. Block A is resting on a table with **frictionless coefficient**,  $\mu_s = 0.3$ ,  $\mu_k = 0.2$ . Block A is released from rest, calculate the Tensions  $T_{AB}$  and Acceleration  $a$ . The rope is massless, and there is **no friction** between the rope and pulley.



Draw FBD B:

$$\text{Y-comp: } T_{AB} - M_B g = -M_B a \quad [1]$$

Draw FBD A:

$$\text{Y-comp: } F_{NA} = 39.2 \text{ N}$$

Maximum static friction  $f_{s,max} = F_{NA} \mu_s = 11.76 \text{ N}$ . Will it move?

$M_B g$  make A move **right**:  $M_B g - f_s = 66.64 \text{ N} > 0$

It will move! Friction is kinetic,  $f = f_k = F_{NA} \mu_k = 7.84 \text{ N}$

$$\text{X-comp: } T_{AB} - f_k = M_A a,$$

$$T_{AB} = f_k + M_A a \quad [2]$$

Solution: Subs [2] into [1]

$$f_k + M_A a - M_B g = -M_B a \rightarrow M_B g - f_k = (M_B + M_A) a$$

$$a = \frac{M_B g - f_k}{M_B + M_A} = \frac{8 \text{ kg} \times 9.8 \text{ m} \cdot \text{s}^{-2} - 7.84 \text{ N}}{8 \text{ kg} + 4 \text{ kg}} = 5.88 \text{ m} \cdot \text{s}^{-2}$$

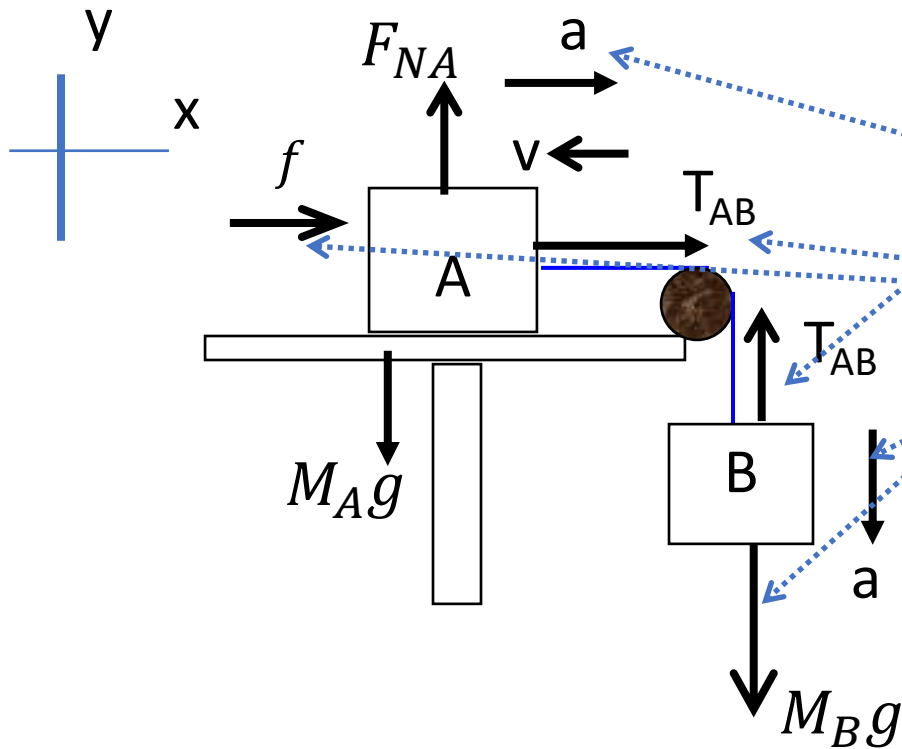
$$\text{Use [2]} \quad T_{AB} = f_k + M_A a = 7.84 \text{ N} + 4 \text{ kg} \times 5.88 \text{ m} \cdot \text{s}^{-2} = 31.36 \text{ N}$$

Verify with [1]

$$T_{AB} = 8 \text{ kg} (g - a) = 31.36 \text{ N}$$

# 2-Body with friction II

In the diagram below block A has a mass of 4.00 kg and block B has mass 8.00 kg. Block A is on a table with **frictionless coefficient**,  $\mu_s = 0.3$ ,  $\mu_k = 0.2$ , and **moving left**. Calculate the Tensions  $T_{AB}$  and Acceleration  $a$ . The rope is massless, and there is **no friction** between the rope and pulley. Will the acceleration increase compare to the last problem?



Draw FBD B:

$$\text{Y-comp: } T_{AB} - M_B g = -M_B a \quad [1]$$

Draw FBD A:

$$\text{Y-comp: } F_{NA} = 39.2N$$

It already moving! Friction is kinetic,  $f = f_k = F_{NA} \mu_k = 7.84N$

$$\text{X-comp: } T_{AB} + f_k = M_A a,$$

$$T_{AB} = -f_k + M_A a \quad [2]$$

Solution: Subs [2] into [1]

$$-f_k + M_A a - M_B g = -M_B a \rightarrow M_B g + f_k = (M_B + M_A) a$$

$$a = \frac{M_B g + f_k}{M_B + M_A} = \frac{8kg \times 9.8m \cdot s^{-2} + 7.84N}{8kg + 4kg} = 7.19m \cdot s^{-2}$$

$$\text{Use [2]} \quad T_{AB} = -f_k + M_A a = -7.84N + 4kg \times 7.19m \cdot s^{-2} = 20.92N$$

Verify with [1]

$$T_{AB} = 8kg(g - a) = 20.88N$$